Code No: R1931025





	III B. Tech I Semester Regular Examinations, February-2022 MICROPROCESSORS AND MICROCONTROLLERS (Electrical and Electronics Engineering)						
	Time:	3 hours Max. Marks	s: 75				
		Answer any <b>FIVE</b> Questions <b>ONE</b> Question from <b>Each unit</b> All Questions Carry Equal Marks					
		<u>UNIT-I</u>					
1.	a)	Draw and explain the register organization of 8086 and mention typical application of each register.	[8M]				
	b)	Explain the various addressing modes of 8086 with examples. <b>(OR)</b>	[7M]				
2.	a)	Explain in detail about the flag register of 8086 microprocessor.	[8M]				
	b)	Explain the architecture of 80386 microprocessor with a neat sketch.	[7M]				
~	``	UNIT-II					
3.	a)	Explain how an analog-to-digital converter is interfaced to 8086	[8M]				
	b)	Explain different modes of operation of 8255.	[7M]				
4.	a)	<b>(OR)</b> Bring out the differences between static RAM and dynamic RAM.	[8M]				
	∽, Ъ)	Design a stonger motor controller and write on ALD to retate the	[2]]				
	IJ	shaft of a 4-phase stepper motor with 200 rotor teeth, for rotations through an angle of 1350 in 2 seconds.	[7][1]				
5.	a)	Draw and discuss the internal architecture of 8259.	[8M]				
	b)	Explain the functions of following signals of 8257: (i) HLDA (ii) AEN	[7M]				
		(11) MARK					
6.	a)	Explain the operation of 8251 (USART). What are its various modes of operation?	[8M]				
	b)	Discuss the properties of DMA request inputs of 8257.	[7M]				
7.	a)	Enlist the salient features of 8051 family of microcontrollers.	[8M]				
	b)	Discuss any four signals description of 8051.	[7M]				
8.	a)	List the applications of microcontrollers. And explain each of it briefly.	[8M]				
	b)	What are the interrupts of 8051? Explain them briefly.	[7M]				

Code	No	R1931025	
Couc	но.	<b>KI90102</b> 0	

R19

**SET** - 1

## <u>UNIT-V</u>

9.	a)	Explain different I/O ports presented in PIC controller and draw	[8M]				
		the necessary diagram for it.					
	b)	Explain the features of ARM controller in detail.					
		(OR)					
10.	a)	Explain the different thumb programming model of ARM	[8M]				
		controller with suitable examples.					
	b)	Draw and explain different timers presented in PIC controller.					

\*\*\*\*

2 of 2